

Algorithms and Data Structures

5th Lecture: Divide and Conquer

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Outline

- Recursion
- Divide and Conquer Approach
- Merge Sort

Recursion

- A recursive function is a function which calls itself recursively.
- The recursive function should be terminated by a specified condition.

Recursive Function: An Example

```
toBinary(x)
    if x > 0
        toBinary(x/2)
    print x%2
```

call toBinary(input)

Input

86₍₁₀₎

Output

1010110₍₂₎

toBinary(1)	→	1
toBinary(2)	→	0
toBinary(5)	→	1
toBinary(10)	→	0
toBinary(21)	→	1
toBinary(43)	→	1
toBinary(86)	→	0

Divide and Conquer Approach

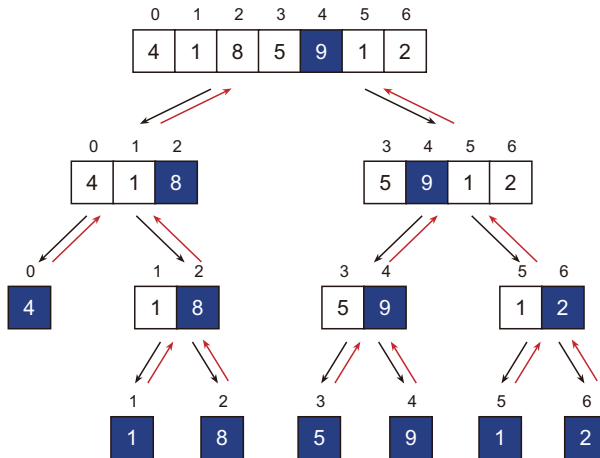
- Many useful algorithms are recursive in structure: to solve a given problem, they call themselves recursively one or more times to deal with closely related subproblems.
- These algorithms typically follow a divide and conquer approach:
 - 1 **[Divide]** they break the problem into several subproblems that are similar to the original problem but smaller in size,
 - 2 **[Conquer]** solve the subproblems recursively, and then
 - 3 **[Combine]** combine these solutions to create a solution to the original problem.

Divide and Conquer Algorithm: An Example

- Recursive divide and conquer solution for finding the maximum.

```
findMax(A, left, right)
    m = (left + right)/2
    if left == right-1
        return A[left]
    else
        u = findMax(A, left, m)
        v = findMax(A, m, right)
        if u > v
            return u
        else
            return v
```

Finding the Maximum



Analysis

```
findMax(A, left, right)
    m = (left + right)/2      const
    if left == right-1      const
        return A[left]      const
    else
        u = findMax(A, left, m)    T(n/2)
        v = findMax(A, m, right)  T(n/2)
        if u > v                const
            return u              const
        else
            return v              const
```


Recurrence

- When an algorithm contains a recursive call to itself, its running time can often be described by a recurrence equation or recurrence, which describes the overall running time on a problem of size n in terms of the running time on smaller inputs.

Analysis of Finding the Maximum

- We set up recurrence for Finding the Maximum.
 - 1 **[Divide]** The divide step computes the middle of subarray, which takes constant time. Thus, $O(1)$.
 - 2 **[Conquer]** We recursively solve two subproblems, each of size $n/2$, which contributes $2T(n/2)$ to the running time.
 - 3 **[Combine]** The comparison between two maximum values in two n -element subarrays takes time $O(1)$.
- The recurrence for the worst-case running time $T(n)$ of Finding the Maximum is

$$T(n) = \begin{cases} c & (n = 1) \\ 2T(n/2) + c & (n > 1) \end{cases}$$

Solving Recurrence

- The algorithm takes linear time.

$$\begin{aligned}T(n) &= 2T(n/2) + c \\&= 2(2T(n/4) + c) + c \\&= 2(2(2T(n/8) + c) + c) + c \\&\dots \\&= 2(2(\dots(2T(1) + c)\dots) + c) + c \\&= 2(2(\dots(2c + c)\dots) + c) + c \\&= (2n - 1)c\end{aligned}$$

Merge Sort

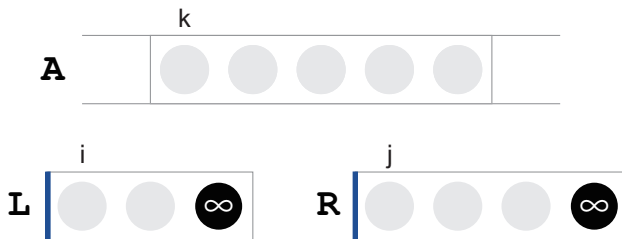
- The Merge Sort algorithm closely follows the divide and conquer paradigm. Intuitively, it operates as follows.
 - 1 **[Divide]** Divide the n -element sequence to be sorted into two subsequences of $n/2$ elements each.
 - 2 **[Conquer]** Sort the two subsequences recursively using Merge Sort.
 - 3 **[Combine]** Merge the two sorted subsequences to produce the sorted answer.
- The key operation of the Merge Sort algorithm is the merging of two sorted sequences in the **[Combine]** step.

Merge Sort: Merge

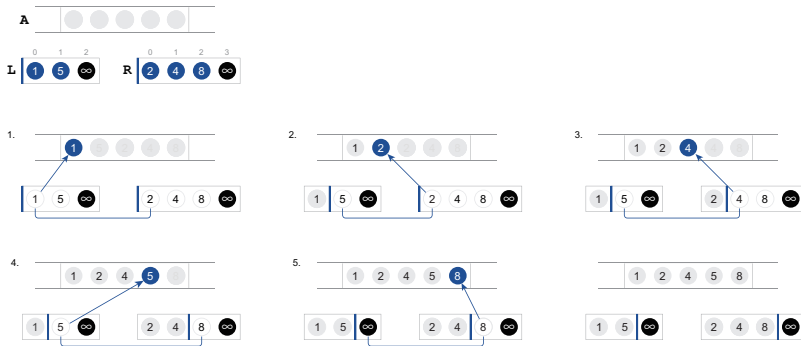
```
merge(A, l, m, r)
    n1 = m - 1
    n2 = r - m
    create an array L[0..n1]
    create an array R[0..n2]
    for i = 0 to n1-1
        L[i] = A[l+i]
    for j = 0 to n2-1
        R[j] = A[m+j]
    L[n1] = SENTINEL
    R[n2] = SENTINEL

    i = 0
    j = 0
    for k = l to r-1
        if L[i] < R[j]
            A[k] = L[i]
            i = i+1
        else
            A[k] = R[j]
            j = j+1
```

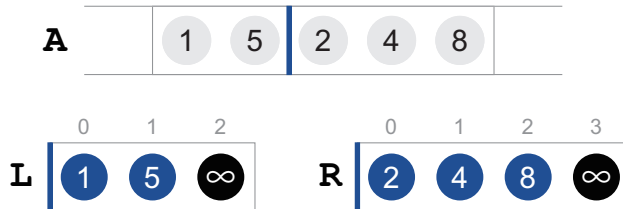
Variables for Merge



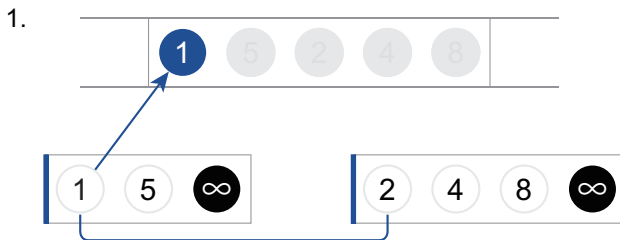
Merge



Merge (0)

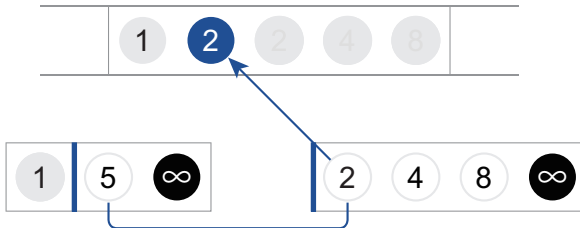


Merge (1)

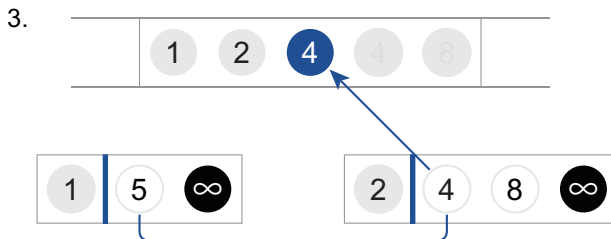


Merge (2)

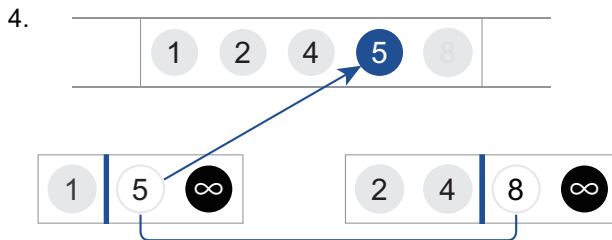
2.



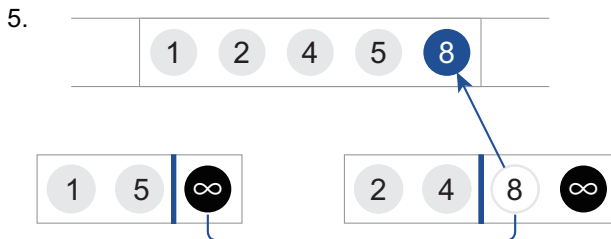
Merge (3)



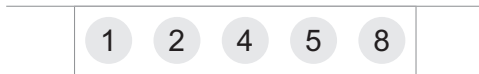
Merge (4)



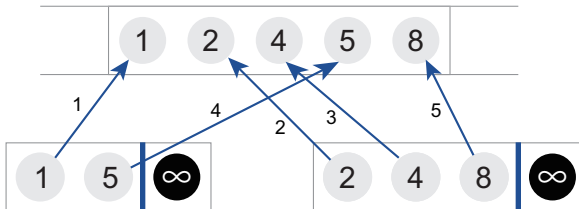
Merge (5)



Merge (6)



Merge (7)

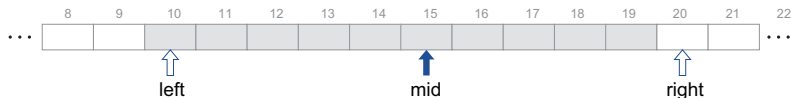


Merge Sort

```
mergeSort(A, left, right)
    if left + 1 < right
        mid = (left + right)/2
        mergeSort(A, left, mid)
        mergeSort(A, mid, right)
        merge(A, left, mid, right)
```

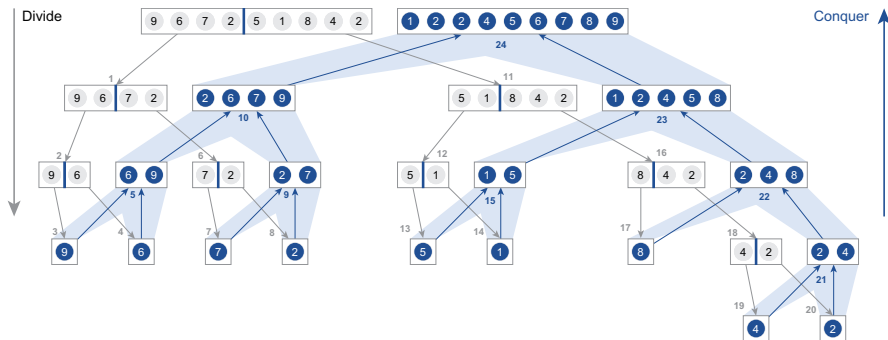
- To sort the entire sequence $A = (A[0], A[1], \dots, A[n-1])$, we make the initial call `mergeSort(A, 0, n)`.

Variables for the Merge Sort Algorithm



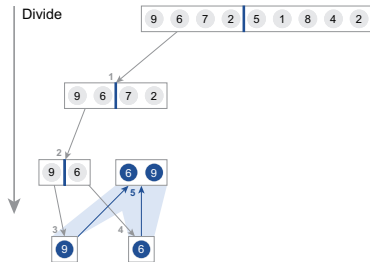
The target of sorting is managed by a half-open interval $[left, right)$.

Merge Sort



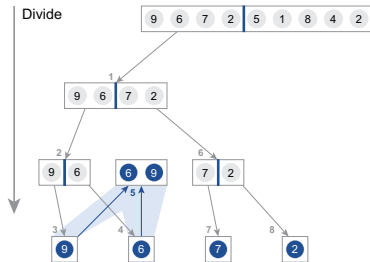
- The operation of Merge Sort on the array $A = \{9, 6, 7, 2, 5, 1, 8, 4, 2\}$. The lengths of the sorted sequences being merged increase as the algorithm progresses from bottom to top.

Merge Sort (1-5)



Conquer

Merge Sort (6-8)

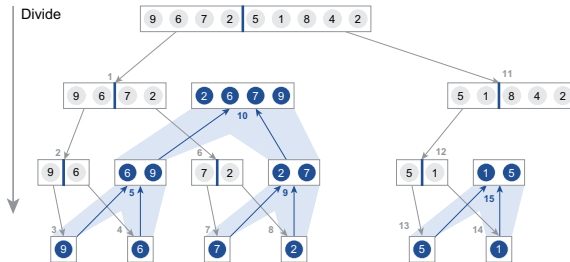


Conquer

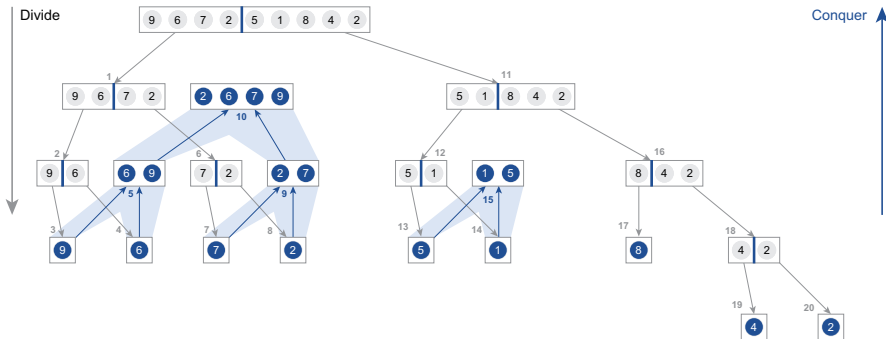
Merge Sort (9-10)



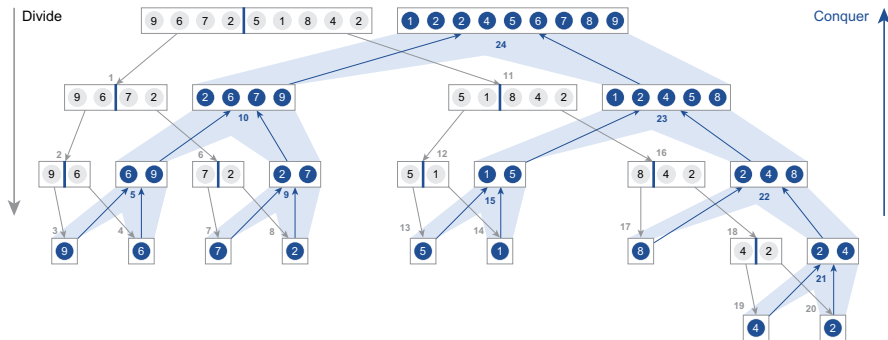
Merge Sort (11-15)



Merge Sort (16-20)



Merge Sort (21-24)



Analysis of Merge Sort (1)

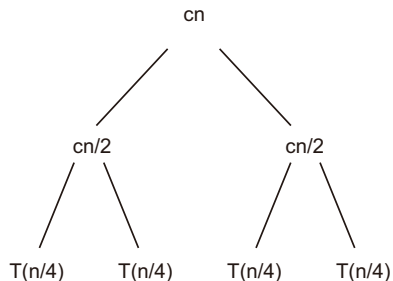
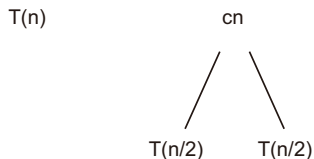
- We set up recurrence for Merge Sort.

- 1 **[Divide]** The divide step computes the middle of subarray, which takes constant time. Thus, $O(1)$.
- 2 **[Conquer]** We recursively solve two subproblems, each of size $n/2$, which contributes $2T(n/2)$ to the running time.
- 3 **[Combine]** The Merge procedure on an n element subarray takes time $O(n)$

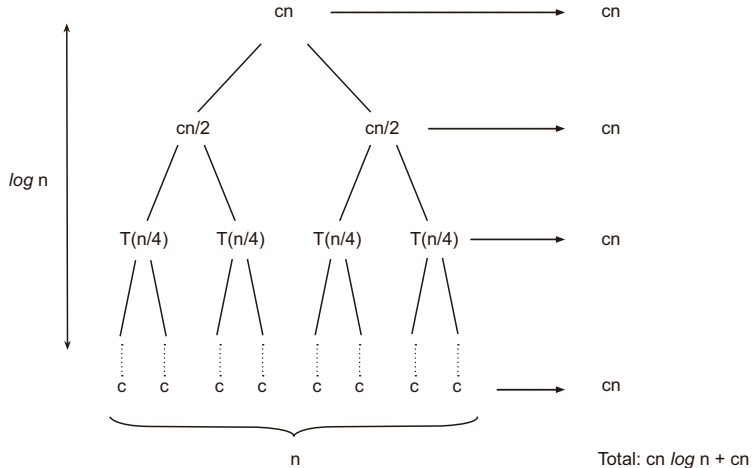
- The recurrence for the worst-case running time $T(n)$ of Merge Sort is

$$T(n) = \begin{cases} c & (n = 1) \\ 2T(n/2) + cn & (n > 1) \end{cases}$$

Analysis of Merge Sort (2)



Analysis of Merge Sort (3)



Analysis of Merge Sort (4)

- Merge sort is a fast algorithm with $O(n \log n)$ in the worst case.
- Merge sort is stable because it does not swap elements which are located separately.
- Merge sort is an external sorting algorithm that requires another array in addition to the array that manages the input data.

Reference

- 1 Introduction to Algorithms (third edition), Thomas H.Cormen, Charles E. Leiserson, Ronald L. Rivest, and Clifford Stein. The MIT Press, 2012.